Decompiling x86 Deep Neural Network Executables

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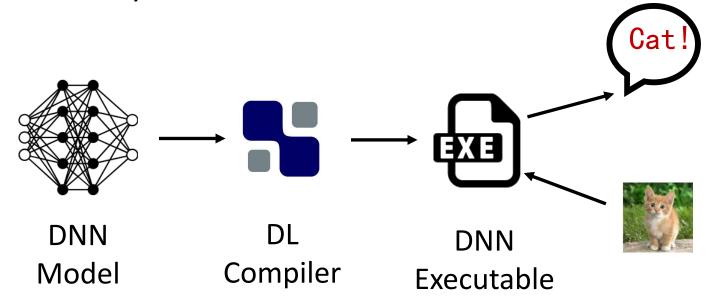
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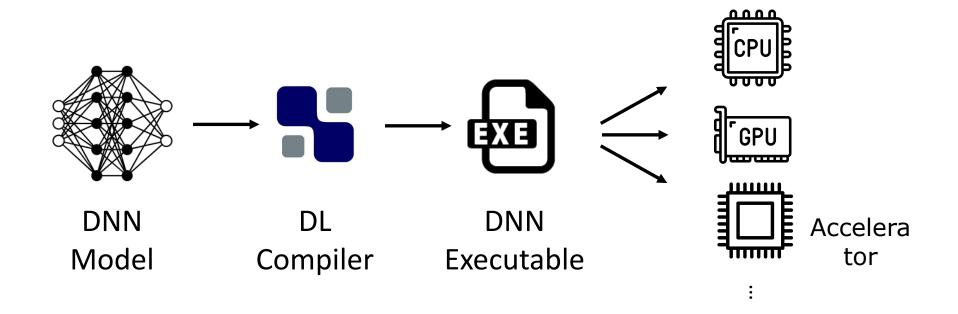
DNN Executable

- What is DNN executable?
 - Output of deep learning compilers.
 - Performing the DNN model inference at runtime.
 - In standalone binary format.



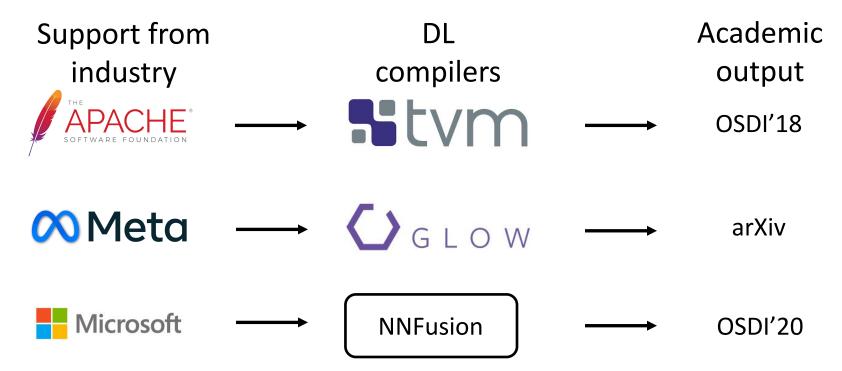
DNN Executable

- Why we need DNN compilation/executable?
 - To fully leverage low-level hardware primitives for fast model inference.
 - To deploy DNN models on heterogeneous hardware devices.



DL Compiler

 Many resources from academia and industry have been devoted to this field.



Problem

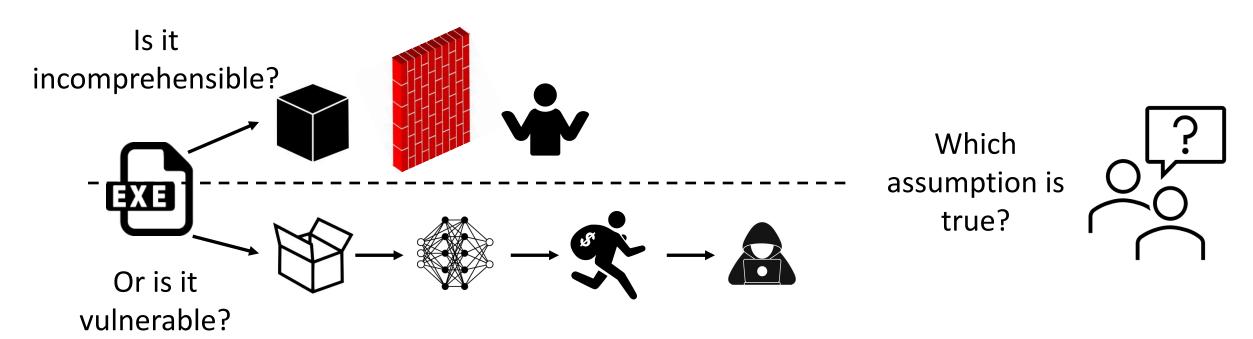
• Currently, DL compiler community mainly focuses on performance

- Our questions:
 - What is the difference between DNN exe and traditional exe?
 - Can we do reverse engineering on DNN executable?



Problem

 Specifically, should we view a DNN executable as a black-box or a white-box?



Challenges

 The traditional software reverse engineering techniques are unable to tackle DNN executables.

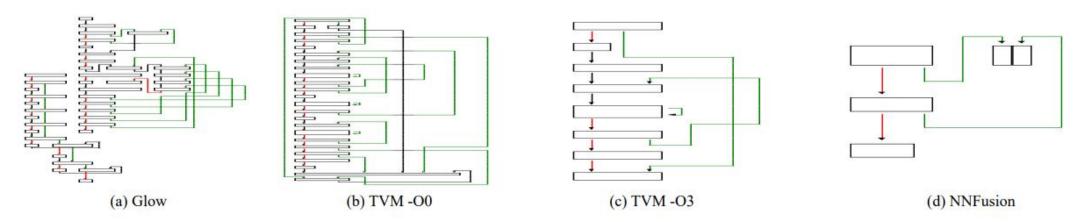


Figure 2: Compare CFGs of a Conv operator in VGG16 compiled by different DL compilers. TVM refers to enabling no optimization as "-O0" while enabling full optimizations as "-O3". Glow and NNFusion by default apply full optimizations.

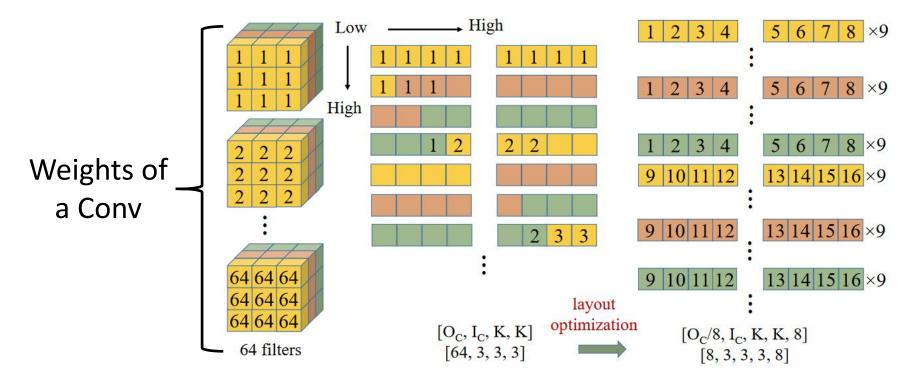
Challenges

Complex data flow

```
v52 = (m128)*(unsigned int *)(v7 + 4 * v29 + 1024);
             v53 = mm \text{ shuffle ps}(v52, v52, 0);
455
             v159 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v42), v53), v159);
             v160 = mm \text{ add ps}(mm \text{ mul ps}(*(m128 *)(v8 + 4 * v45), v53), v160);
457
             v161 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v46), v53), v161);
458
             v162 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v47), v53), v162);
459
             v163 = mm \text{ add ps}(mm \text{ mul ps}(*(m128 *)(v8 + 4 * v48), v53), v163);
             v164 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v49), v53), v164);
461
             v165 = mm \text{ add ps}(mm \text{ mul ps}(*(m128 *)(v8 + 4 * v50), v53), v165);
462
             v166 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v51), v53), v166);
463
             v54 = (m128)*(unsigned int *)(v7 + 4 * v29 + 1536);
             v55 = mm \text{ shuffle ps}(v54, v54, 0);
             v167 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v42), v55), v167);
             v168 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v45), v55), v168);
467
             v169 = mm \text{ add ps}(mm \text{ mul ps}(*(m128 *)(v8 + 4 * v46), v55), v169);
468
             v170 = _{mm_add_ps(_{mm_mul_ps(*(__m128 *)(v8 + 4 * v47), v55), v170);}
             v171 = mm \text{ add ps}(mm \text{ mul ps}(*(m128 *)(v8 + 4 * v48), v55), v171);
470
             v172 = _mm_add_ps(_mm_mul_ps(*(_m128 *)(v8 + 4 * v49), v55), v172);
471
             v173 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v50), v55), v173);
472
             v174 = mm \text{ add ps(} mm \text{ mul ps(*(} m128 *)(v8 + 4 * v51), v55), v174);
473
             v56 = (m128)*(unsigned int *)(v7 + 4 * v29 + 2048);
474
             v57 = mm \text{ shuffle ps}(v56, v56, 0);
475
```

Challenges

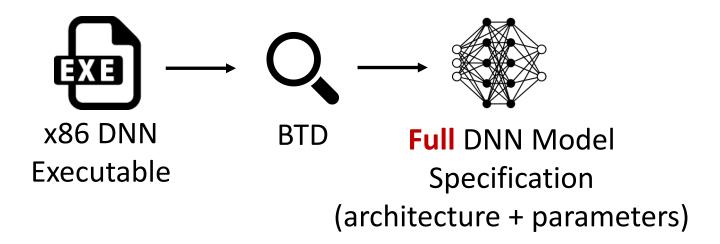
- Hardware-aware optimizations during compilation.
 - memory layout optimization
 - > better memory locality & compatible with SIMD



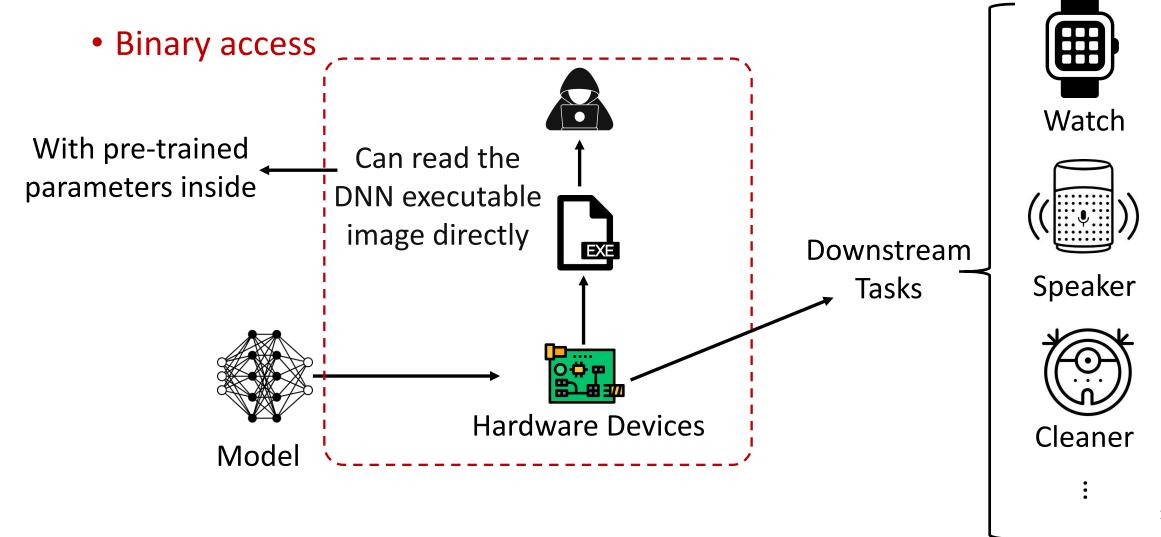
Our Work

• The traditional software reverse engineering techniques are unable to tackle DNN executables.

• We propose BTD (Bin-To-DNN), the first DNN executable decompiler.



Threat Model



Observation

DL compilers generate distinct low-level code but retain operator highlevel semantics, because DNN operators are generally defined in a clean and rigorous manner.

E.g., mathematical definition of Conv:

$$\operatorname{out}(N_i, C_{\operatorname{out}_j}) = \operatorname{bias}(C_{\operatorname{out}_j}) + \sum_{k=0}^{C_{\operatorname{in}}-1} \operatorname{weight}(C_{\operatorname{out}_j}, k) \star \operatorname{input}(N_i, k)$$

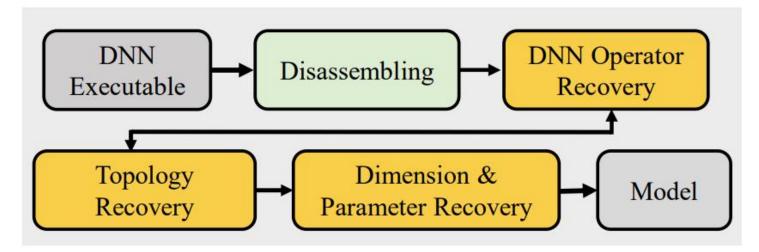
Semantics of different implementation should be consistent!

Observation

- Differences between DNN executables and general software
 - > overwhelming arithmetic operations
 - → hard to understand
 - ➤only one valid execution path!
 - →no path explosion problem
 - →get high-level semantics with symbolic execution!
- Give us an opportunity to summarize the semantics from low-level binary code

Workflow

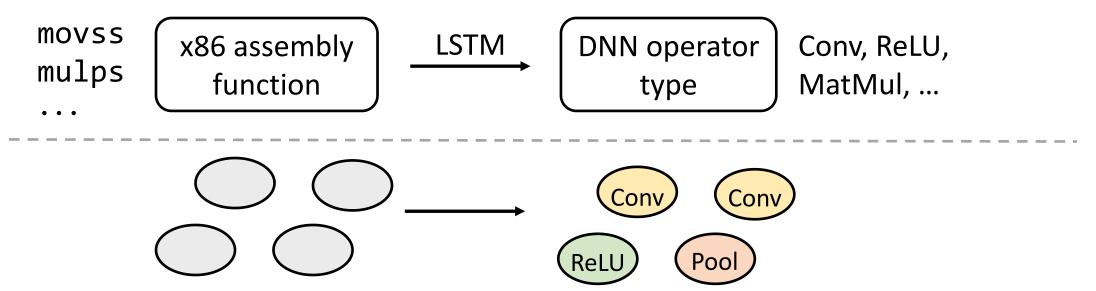
• BTD consists of 3 steps: operator recovery, topology recovery, dimension & parameter recovery.



• BTD is able to recover full model specification (including operators, topologies, dimensions, and parameters) from DNN executable.

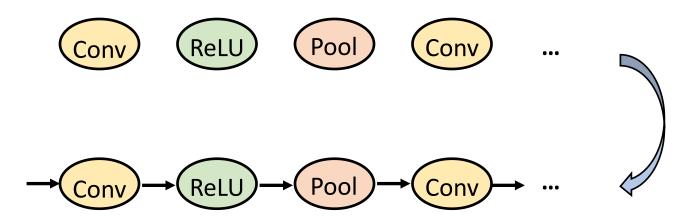
Step 1: DNN Operator Recovery

- We train an LSTM model to map assembly functions to DNN operators.
 - Treat x86 opcodes as language tokens.
 - Segment x86 opcodes using Byte Pair Encoding (BPE).
 - Multiclass classification task



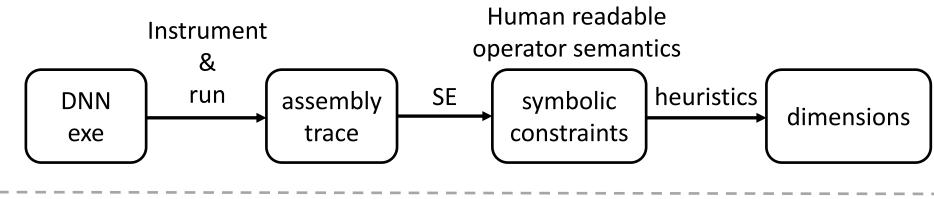
Step 2: Topology Recovery

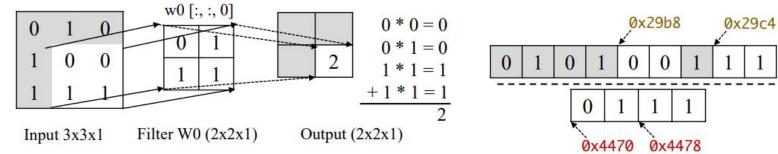
- DL compilers compile DNN operators into assembly functions and pass inputs and outputs as memory pointers through function arguments.
- We hook every call site to record the memory address, and chain operators into computation graph.



Step 3: Dimension & Parameter Recovery

 Idea: we launch trace-based symbolic execution (SE) to infer dimensions and localize parameters for DNN operators





(a) One Convolution Operation

(b) Memory Layout and Addresses

output =
load(0x29b8,4) * load(0x4470,4) +
load(0x29bc,4) * load(0x4474,4) +
load(0x29c4,4) * load(0x4478,4) +
load(0x29c8,4) * load(0x447c,4)

mem address: input locations

mem address: weight locations

(c) Corresponding Symbolic Formula

Step 3: Dimension & Parameter Recovery

- Symbolic constraints extracted from vastly different binaries are mostly consistent.
 - Our (symbolic constraint-based) heuristics are general and cross-compilers

```
output =
                                                output =
                                                (0 +
 max(
 (load(0x22a5a84,4) * load(0x7e1f54,4) +
                                                load(0x29cfe98,4) * load(0x293cd60,16) +
  load(0x22a5a7c,4) * load(0x7e1f4c,4) +
                                                load(0x29cfe9c,4) * load(0x293cde0,16) +
  load(0x22a5a80,4) * load(0x7e1f50,4) +
                                                load(0x29cfea0,4) * load(0x293ce60,16) +
  load(0x22a5a78,4) * load(0x7e1f48,4) +
                                                load(0x29cfea4,4) * load(0x293cee0,16) +
  ...),
                                                ...)
 0)
(a) Symbolic Constraint of Glow
                                               (b) Symbolic Constraint of TVM –O0
output =
(0+
  load(0x284dcc8,4) * load(0x7a9180,16) +
                                                mem address: input locations
  load(0x284dccc,4) * load(0x7a9200,16) +
                                                mem address: weight locations
  load(0x284dcd0,4) * load(0x7a9280,16) +
  load(0x284dcd4,4) * load(0x7a9300,16) +
(c) Symbolic Constraint of TVM –O3
```

Step 3: Dimension & Parameter Recovery

 We infer operator dimensions (e.g., kernel size, #input channels, #output channels, stride) from extracted symbolic constraints with a set of heuristics.

- Then instrument the DNN executable to dump parameters (e.g., weights, biases) during execution.
- With all extracted information (i.e., operator types, topologies, dimensions, and parameters) we can rebuild a new model showing identical behavior with the original model.

Evaluation

• 8 version of 3 state-of-the-art, production level DL compilers

Table 1: Compilers evaluated in our study.

Tool Name	Publication	Developer	Version (git commit)
			v0.7.0
TVM [20]	OSDI '18	Amazon	v0.8.0
			v0.9.dev
			2020 (07a82bd9fe97dfd)
Glow [77]	arXiv	Facebook	2021 (97835cec670bd2f)
			2022 (793fec7fb0269db)
NNEusion [59]	OSDI '20	Microsoft	v0.2
NNFusion [58]	USDI 20	Wheresoft	v0.3

Evaluation

- 7 models cover all operators used in the CV models from ONNX Zoo https://github.com/onnx/models
- Real-world image classification models trained on ImageNet

Table 2: Statistics of DNN models and their compiled executables evaluated in our study.

Model #Deremeters	#Operators	TVM -O0		TVM -O3		Glow -O3		
Model #Parameters		Avg. #Inst.	Avg. #Func.	Avg. #Inst.	Avg. #Func.	Avg. #Inst.	Avg. #Func.	
Resnet18 [36]	11,703,912	69	49,762	281	61,002	204	11,108	39
VGG16 [81]	138,357,544	41	40,205	215	41,750	185	5,729	33
FastText [18]	2,500,101	3	9,867	142	7,477	131	405	14
Inception [83]	6,998,552	105	121,481	615	74,992	356	30,452	112
Shufflenet [99]	2,294,784	152	56,147	407	34,637	228	33,537	59
Mobilenet [41]	3,487,816	89	69,903	363	46,214	228	37,331	52
Efficientnet [84]	12,966,032	216	89,772	546	49,285	244	13,749	67

Results

• Step 1: DNN operator inference

Table 3: Average accuracy of DNN operator inference.

Model		Glow		TVM -O0			TVM -O3		
$\frac{1}{2}$	2020	2021	2022	v0.7	v0.8	v0.9.dev	v0.7	v0.8	v0.9.dev
ResNet18	100%	100%	100%	99.79%	99.84%	100%	98.15%	99.06%	99.69%
VGG16	100%	100%	100%	99.95%	99.79%	99.57%	99.75%	100%	100%
Inception	100%	100%	100%	99.98%	99.88%	99.98%	100%	100%	100%
ShuffleNet	100%	100%	100%	99.96%	99.82%	100%	99.62%	99.71%	99.31%
MobileNet	100%	100%	100%	99.35%	99.46%	99.40%	99.80%	100%	100%
EfficientNet	100%	100%	100%	99.65%	99.68%	99.59%	99.81%	99.91%	100%

Results

- Step 3:
 - Parameter layout/dimension inference.

- BTD fails on two cases
 - Because of DL compiler optimizations
 - (details in our paper)

Table 10: Parameter/dimension inference. Lines 2–8 report each executable's total #dimensions, correctly-inferred dimensions, and accuracy rate for dimension inference. Lines 9–15 report total #parameters and accuracy rate for parameter inference. Different versions of the same compiler produce the same results, therefore we merge their columns.

Model	Glow	TVM -O0	TVM -03		
Model	(2020, 2021, 2022)	(v0.7, v0.8, v0.9.dev)	(v0.7, v0.8, v0.9.dev)		
ResNet18	65/65/100%	51/47/92.15%	78/78/100%		
VGG16	54/54/100%	59/59/100%	52/52/100%		
FastText	7/7/100%	7/7/100%	7/7/100%		
Inception	235/235/100%	223/223/100%	222/222/100%		
ShuffleNet	82/82/100%	71/71/100%	71/71/100%		
MobileNet	124/124/100%	144/144/100%	125/125/100%		
EfficientNet	133/133/100%	133/133/100%	132/132/100%		
ResNet18	11,684,712/100%	11,703,912/99.37%	11,684,712/99.37%		
VGG16	138,357,544/100%	138,357,544/100%	138,357,544/100%		
FastText	2,500,101/100%	2,500,101/100%	2,500,101/100%		
Inception	6,998,552/100%	6,998,552/100%	6,998,552/100%		
ShuffleNet	2,270,514/100%	2,294,784/100%	2,270,514/100%		
MobileNet	3,487,816/100%	3,487,816/100%	3,487,816/100%		
EfficientNet	12,950,384/100%	12,966,032/100%	12,950,384/100%		

Results

BTD is able to extract functional models in most cases.

Table 11: Recompilation. "NA" means that some errors in DNN models are not fixed, and thus the rebuilt models manifest inconsistent behavior.

Model	Glow	TVM -O0	TVM -O3 (v0.7, v0.8, v0.9.dev)		
Micoci	(2020, 2021, 2022)	(v0.7, v0.8, v0.9.dev)			
ResNet18	100%	100% (with fixing)	$NA \rightarrow 100\%$		
VGG16	100%	100%	100%		
FastText	100%	100%	100%		
Inception	100%	100%	100%		
ShuffleNet	100%	100%	100%		
MobileNet	100%	100%	100%		
EfficientNet	100%	100%	100%		

• Thus, we can enable white-box attacks (e.g., adversarial example) on a black-box, obscure DNN executable

Implement

- BTD is released at: https://github.com/monkbai/DNN-decompiler
 - With a demo docker image
- With badges Available, Functional, Reproduced







Takeaways

• It is hard to reverse DNN executables with existing techniques due to complex control/data flow.

• There is only one execution path, giving us an opportunity to summarize the semantics with symbolic execution.

• We propose BTD (Bin-To-DNN), the first DNN executable decompiler.

Thanks

Q&A

• BTD: https://github.com/monkbai/DNN-decompiler